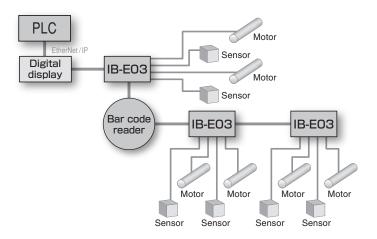




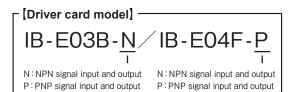
# IB-E03B/04F



# EtherNet/IP based high speed communication



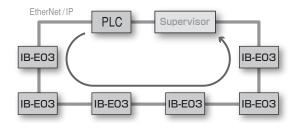
# [Applicable MDR models] IB-E03B····FE series, FP series IB-E04F····KT series

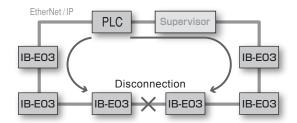




EtherNet/IP is the same Ethernet used in your front office combined with a common protocol that provides robust, real time networking for motion, drive, safety, process and high speed discrete control. It is an implementation of the Common Industrial Protocol (CIP). Custom programmable ladder logic is available for fine tuning your specific application. With direct connectivity over Ethernet, simple, seamless and high speed network communication system can be built from sensor signal through information data.

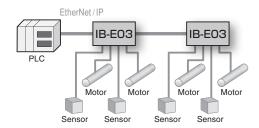
### **Device Level Ring (DLR) though Supervisor**





 Device Level Ring (DLR) provides fault-tolerant network design for both daisy chain and linear topology. This ensures continued network communication

#### Simplified wiring





- IB-E03B has photo sensor wiring ports allowing seamless connections of signals and information.
- IB-E03B controls two MDR units, and simple LAN cable wiring connects multiple IB-E03B units.

## ICE – Itoh Configurator for EtherNet/IP Dedicated PC application software for setting parameters

- Enables autonomous distributed control through local logic setting, allowing the control to make local decision without waiting for high layer command.
- Various monitor functions (MDR failure diagnosis)



Parameter setting

Ladder logic setting

MDR current draw

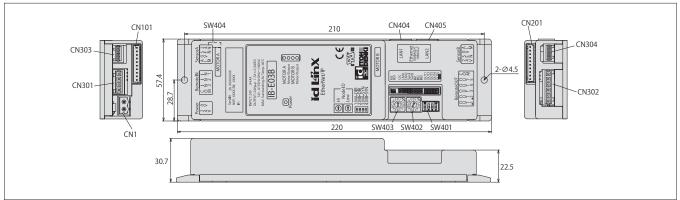
Mar 184 854 Min 184 854 Min 684 814 Aug 648 814





## IB-E03B/04F

#### ■ Dimensions



#### ■ Controller specifications

		IB-E03B	IB-E04F
Motor power	Nominal voltage	24V DC	24V DC
	Static current	0.15A	0.15A
	Peak current	20A (1msec)	20A (1msec)
	Starting current	4.0A	7.0A
Control power	Nominal voltage	24V DC	24V DC
	Current	0.05A	0.05A
LED indication		Power Mot A/B (Motor/Output) STS (Motor status) SEN A/B (Sensor status) Remote IN/OUT LAN 1/2 (Communication) Error	
Protections		7A fuse	10A fuse
Thermal overloa protections	d driver card	95℃	95℃
	motor	105℃	105℃

Brake selection			Electric (dynamic) brake Servo lock brake	
Power		Controller side	231-532/001-000	
conne	ector	Wiring side	231-302/026-000	
Sensor		Controller side	WAGO 733-364	
conne	ector	Wiring side	WAGO 733-104	
Communication		Controller side	TMR 11R-5M2-88 (Hirose)	
conne	ector	Wiring side	RJ45 (Hirose)	
ıtal	Ambient te	mperature	-20 to 40°C	
Environmental conditions	Humidity		≤ 90%Relative Humidity (no condensation)	
	Atmosphere		No corrosive gases	
	Vibration		≦ 1.0G	

#### ■ Communication specifications

ODVA conformance test	CIII	
Protocol	Ethernet (IEEE 802.3)	
Transmission media	Standard Ethernet cable (CAT 5 or over) 100BASE-TX	
Communication speed	10Mbps/100Mbps (automatic negotiation)	
Transmission form	Full duplex/half duplex (Auto negotiation)	
	UL and CSA recognized (pending)	
	UL 508 and CSA C22.2 No.14	
Standard	(Recognized component)	
	◆Category Code No. (CCN): NMMS2, NMMS8	
	●- File No. E33970	

#### ■ Standard accessories

- ●Cross-recessed head screws: M4 x 15
- ●Hexagonal nut: M4

#### Options

Name	Part number	Manufacturer
<ul><li>Motor power connector (CN1)</li></ul>	231-302 / 026-000	WAGO
<ul> <li>Communication connector</li> </ul>	RJ 45	Hirose
<ul> <li>Sensor connector</li> </ul>	733-104	WAGO
<ul> <li>●Control connector</li> </ul>	734-204 (External input)	WAGO
	734-206 (Signal output)	WAGO

#### Applicable model

IB-E03B···FE series

FP series

MDR motor cable should be 10pin connector type in case of using with IB-E03 driver card.

IB-E04F···KT series

Both IB-E04 driver card and KT series roller are equipped 12pin motor connector as a standard.

The roller built-in brake is not applicable.